

Cartilage Thickness: Factors Influencing Multidetector CT Measurements in a Phantom Study¹

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Purpose:

To prospectively assess in a phantom the reconstruction errors and detection limits of cartilage thickness measurements obtained with multidetector computed tomographic (CT) arthrography, as a function of contrast agent concentration, scanning direction, spatial resolution, joint spacing, and tube current, with known measurements as the reference standard.

Materials and Methods:

A phantom with nine chambers was constructed. Each chamber had a nylon cylinder encased by sleeves of aluminum and polycarbonate to simulate trabecular bone, cortical bone, and cartilage. Varying simulated cartilage thicknesses and 10 joint space widths were assessed. On 3 days, the phantom was scanned with and without contrast agent administration and with the chamber axes both perpendicular and parallel to the scanner axis. Images were reconstructed at 1.0- and 0.5-mm intervals. Contrast agent concentration and tube current were varied. The simulated cartilage thickness was determined by using image segmentation. Root mean squared errors and mean residual errors were used to characterize the measurements. The reproducibility of the CT scanner and image segmentation results was determined.

Results:

Simulated cartilage greater than 1.0 mm in thickness was reconstructed with less than 10% error when either no contrast agent or a low concentration (25%) of contrast agent was used. Error increased as contrast agent concentration increased. Decreasing the simulated joint space width to 0.5 mm caused slight increases in error; however, error increased substantially at joint spaces narrower than 0.5 mm. Errors in measurements derived from anisotropic CT data were greater than errors in measurements derived from isotropic data. Altering the tube current did not substantially affect reconstruction errors.

Conclusion:

The study revealed lower boundaries and the repeatability of simulated cartilage thickness measurements obtained by using multidetector CT arthrography and yielded data pertinent to choosing the contrast agent concentration, joint space width, scanning direction, and spatial resolution to reduce reconstruction errors.

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Evidence suggests that multidetector computed tomographic (CT) arthrography may be more sensitive than magnetic resonance (MR) imaging for depicting cartilaginous lesions (1–5) and quantifying cartilage thickness (6). However, fat-suppressed spoiled gradient-recalled acquisition in the steady state is still considered the best protocol for imaging articular cartilage (7–16). Although a substantial body of research (17–22) has been performed to examine MR cartilage reconstruction errors, less attention has been given to CT arthrography (6,18,23). Nevertheless, MR data-derived estimates of cartilage thickness are often validated by means of direct comparison with CT arthrography results (18,19); this protocol might erroneously imply that CT arthrography is the reference standard for such estimations.

Examinations performed to compare cartilage thickness measurements estimated from CT arthrography data with measurements obtained from physical examinations of anatomic sections generally have been qualitative assessments (18,23). To our knowledge, in only one study have quantitative cartilage thickness measurements been compared between reconstructed multidetector CT arthrograms and excised tissue samples (6). However, the use of harvested cartilage plugs in that study limited the range of cartilage thicknesses that could be analyzed.

Evidence suggests that cartilage may actually swell during the early stages of osteoarthritis (24). Therefore, it would be useful to quantify cartilage thickness by using CT arthrography in patients

who report having pain that may be related to osteoarthritis but do not have direct radiographic evidence of thinning or localized defects. In terms of experimental investigations of cartilage contact mechanics performed by using cadaveric tissue, the quantification of differences in reconstruction errors between standard CT and CT arthrography would help to clarify whether cadaveric joints should be completely dissected and imaged with air or the joint capsule should be left intact.

The boundaries of cartilage thickness detection—and hence the ultimate reconstruction error—with multidetector CT arthrography remain unknown. In addition, to our knowledge, the influence of imaging parameters on the ability to detect and reconstruct articular cartilage from multidetector CT arthrography data had not been assessed. Thus, the purpose of our study was to prospectively assess in a phantom the reconstruction errors and detection limits of cartilage thickness measurements obtained with multidetector CT arthrography, as a function of contrast agent concentration, scanning direction, spatial resolution, joint spacing, and tube current, with known measurements as the reference standard.

Materials and Methods

Phantom Description

An imaging phantom to quantify the error in reconstructing cartilage thickness was designed and manufactured (CNA Precision Machine, Ogden, Utah) (Fig 1). The phantom body was constructed of nylon (Natural Cast Nylon; Professional Plastics, Fullerton, Calif). Nine chambers were drilled into the phantom body (Fig 1). Each cham-

ber was composed of a central nylon cylinder encased by cylindrical sleeves of aluminum and polycarbonate (Standard Polycarbonate; Professional Plastics). The central nylon cylinder simulated trabecular bone; the cylindrical sleeve of aluminum, cortical bone; and the outer cylindrical sleeve of polycarbonate, cartilage (Fig 1b). All aluminum cylinders were manufactured to a wall thickness of 1.00 mm to represent cortical bone with a constant thickness. The polycarbonate cylindrical sleeves were manufactured to wall thicknesses of 0.25, 0.50, 0.75, 1.00, 2.00, and 4.00 mm (Fig 1a, phantom chambers 1–6). An outer polycarbonate four-prong spacer was press fit into each chamber between the outer layer of simulated cartilage and the adjacent nylon phantom body (Fig 1b). The spacer held the central cylinders securely in place and provided a joint space that could be filled with contrast agent. The joint space width in phantom chambers 1–6 (Fig 1a) was held constant at 2.0 mm. Varying joint space widths (0.25, 0.50, and 1.00 mm) were used with a constant simulated cartilage thickness of 2.00 mm in the remaining three compartments (Fig 1a, phantom chambers 7–9). Finally, nylon-threaded caps were used to seal the fluid inside the chambers. The manufacturer used a micrometer with an accuracy of ± 0.01 mm to determine the wall thickness tolerance of the aluminum and polycarbonate cylindrical sleeves, representing cortical bone and cartilage, respectively.

Advances in Knowledge

- Changing the contrast agent concentration, scanning direction, and/or spatial resolution had the greatest effect on simulated cartilage reconstruction errors; altering the joint spacing and tube current resulted in minor changes.
- The results of our study establish lower boundaries and the repeatability of cartilage thickness measurements with multidetector CT.

Implication for Patient Care

- Careful consideration of the contrast agent concentration, scanning direction, and spatial resolution may reduce errors when reconstructing cartilage with use of the patient's multidetector CT arthrography data.

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Abbreviation:

RMS = root mean squared

Author contributions:

Guarantor of integrity of entire study, J.A.W.; study concepts/study design or data acquisition or data analysis/interpretation, all authors; manuscript drafting or manuscript revision for important intellectual content, all authors; manuscript final version approval, all authors; literature research, all authors; experimental studies, all authors; statistical analysis, A.E.A., J.A.W.; and manuscript editing, all authors

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The tolerance was reported to be within ± 0.07 mm.

Nylon, polycarbonate, and aluminum were chosen as phantom materials because they have x-ray attenuation values similar to those of trabecular bone, cartilage, and cortical bone, respectively (25–28). The size of the phantom (250 \times 250 mm) was representative of a typical field of view used to image diarthrodial joints in humans. The outer diameter of each compartment—that is, the outer boundary of simulated cartilage—was kept constant at 52 mm, while the diameters of the aluminum sleeve and central nylon cylinder were adjusted to between 38 and 46 mm to accommodate differences in cartilage thickness and joint spacing. This range of cylinder diameters is similar to that for femoral and humeral heads in humans reported in the literature (29–31). The range of cartilage thicknesses (0.25–4.00 mm) was chosen to represent the range of articular cartilage thicknesses in humans reported in the literature (32,33).

CT Protocol

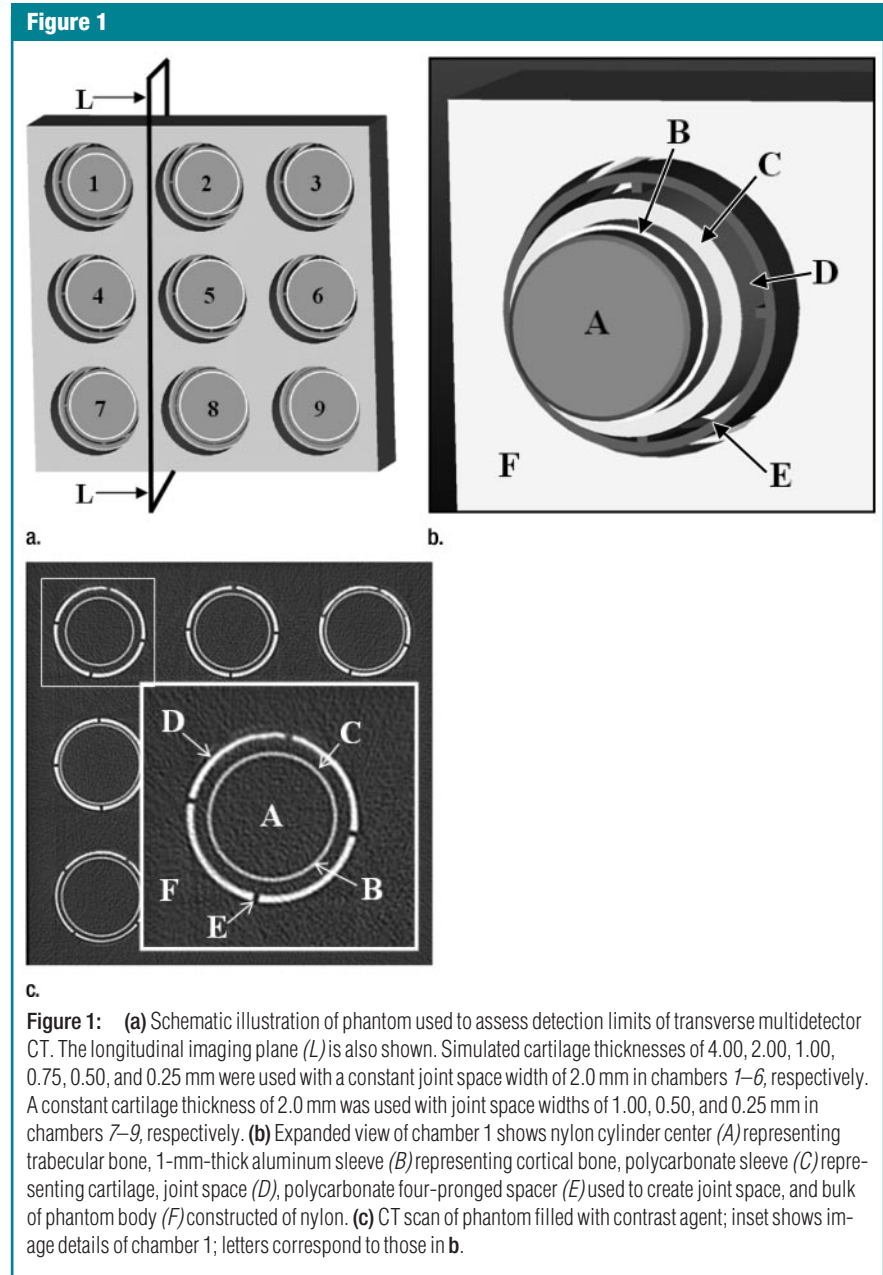
All CT examinations of phantoms were performed with a Somatom Sensation 64 scanner (Siemens Medical Solutions, Malvern, Pa). This scanner makes use of the periodic motion of the focal spot in the longitudinal direction to double the number of simultaneously acquired sections, with the goals of improving spatial resolution and eliminating spiral artifacts, regardless of spiral pitch. The following scanning parameters were kept constant: 120 kVp, 512 \times 512 matrix, 300-mm field of view, and 1-mm section thickness. Six contrast material-enhanced CT examinations and four non-enhanced examinations were performed. The imaging protocol detailed below was performed on three separate days to assess the reproducibility of the CT scanner and segmentation procedure results.

Contrast-enhanced CT.—Iohexol (350 mg of iodine per milliliter) (Omnipaque 350; GE Healthcare, Princeton, NJ) was mixed with 1% lidocaine hydrochloride (Hospira, Lake Forest, Ill) in separate concentrations of 25%, 50%, and 75%.

The phantom was scanned by using a tube current of 200 mAs for each of the three concentrations (three examinations) in the transverse or frontal plane (Fig 1a). The laser guide was used to align the CT section axis perpendicular to the phantom chambers' longitudinal axes and thereby minimize volumetric averaging between sections. Two additional transverse examinations were conducted by using tube currents of 150

and 250 mAs with the phantom filled with a 50% concentration of the contrast agent. To intentionally introduce volumetric averaging, an examination of the phantom filled with a 50% contrast agent concentration was performed parallel to the phantom chambers' longitudinal axis using a tube current of 200 mAs (Fig 1a).

Nonenhanced CT.—To estimate the error in cartilage thickness reconstruc-



tion for disarticulated dissected cadaveric joints, the phantom was imaged when it was not filled with contrast agent. Three nonenhanced examinations were performed in the transverse plane by using tube currents of 150, 200, and 250 mAs. To intentionally introduce volumetric averaging between successive sections, a final nonenhanced CT examination was performed parallel to the phantom chambers' longitudinal axis using a tube current of 200 mAs.

Image Segmentation, Surface Reconstruction, and Thickness Measurement

Phantom image data were transferred to a Linux workstation (Universal Systems, Salt Lake City, Utah) for postprocessing. To assess differences in reconstruction errors between anisotropic ($0.586 \times 1.0 \times 0.586$ mm) and near-isotropic ($0.586 \times 0.5 \times 0.586$ mm) spatial resolution, image data were resampled after the CT examination by using 0.5-mm section intervals for the contrast-enhanced and nonenhanced longitudinal examinations. The use of inner postscanning reconstructions in the transverse plane would have been ambiguous since the curvature of the phantom chambers did not change as sections were imaged in this direction.

Separate splines for the outer surface of the aluminum cylinder (representing cortical bone) and the boundary between the polycarbonate cylinder (representing outer layer of simulated cartilage) and either air (nonenhanced examination) or contrast agent (contrast-enhanced examination) were extracted from the image data. Both automatic and semiautomatic thresholding techniques were applied by using commercial segmentation software (Amira 4.1; Mercury Computer Systems, Chelmsford, Mass).

Each data set was automatically thresholded by using a masking technique available in the segmentation software, which allows the user to highlight pixels over a range of defined attenuation values. For data sets with contrast agent included, the mask was adjusted incrementally until all pixels represent-

ing nylon (the bulk of the phantom body) were excluded. Thus, pixels with attenuation values greater than this masked range were defined as contrast agent and simulated cortical bone, whereas those with attenuation values less than this masked range were defined as simulated cartilage. For the nonenhanced CT data sets, the same masking procedure was used to define the simulated cortical bone boundary; however, the boundary between simulated cartilage and air was defined by reversing the mask such that all pixels representing the nylon body of the phantom were included. As mentioned above, the masking procedure was performed for each CT data set separately to ensure that the appropriate threshold range was chosen independently of alterations in tube current, contrast agent concentration, spatial resolution, or scanning direction. After all data sets were masked, it was later determined that interscan threshold values varied by less than 5%.

Owing to CT volumetric averaging, it was necessary to use a semiautomatic thresholding technique for the data sets in which contrast agent was included. However, this procedure was only required for phantom chambers with simulated cartilage thicknesses of 0.50 and 0.25 mm (Fig 1a, chambers 5 and 6). Simulated cartilage with thicknesses greater than these was effectively segmented by using the automatic method, regardless of contrast agent concentration, tube current, spatial resolution, or scanning direction. For the 0.50- and 0.25-mm chambers, first the baseline automatic threshold value was used to define a general segmentation spline. Next, regions where pixels blended together were separated by using a paintbrush tool available in the segmentation software such that the resulting spline followed the general boundary between simulated cartilage and contrast agent. Although volumetric averaging occurred, the attenuation gradient between contrast agent and simulated cartilage was strong enough to allow easy visual separation. To ensure uniformity, all of the semiautomatic segmentations were performed by the senior author (A.E.A.).

Splines were stacked on top of one another and triangulated by using the marching cubes algorithm (34) to form surfaces that represented the outer surfaces of simulated cortical bone and cartilage. To preserve the native splines of the CT image data, the resulting polygonal surfaces were not altered by means of decimation or smoothing. A published algorithm was used to assign a thickness to each of the nodes that defined the simulated cartilage surface (35). This algorithm has been tested for accuracy by using concentric cylinders with known thicknesses. Reported errors were less than 2% (35).

Error Analysis

Thickness values were analyzed to determine the reconstruction errors and detection limits of multidetector CT and to investigate the influences of tube current, joint spacing, contrast agent concentration, and scanning direction. The overall thickness error for each phantom chamber measurement was assessed by using the root mean squared (RMS) error (E_{RMS}) criteria:

$$E_{\text{RMS}} = \left[\frac{\sum_{i=1}^n (t_i^{\text{CT}} - t^{\text{Phan}})^2}{n} \right]^{1/2}, \quad (1)$$

where the summation (Σ) is over the number of surface nodes (n) from $i = 1$ to n , t_i^{CT} is the thickness of the i th node of the reconstructed surface, and t^{Phan} is the constant thickness assessed by means of direct manufacturer measurement of the phantom. The mean residual error (MRE) was calculated as follows to determine the direction of the error:

$$\text{MRE} = \left[\frac{\sum_{i=1}^n (t_i^{\text{CT}} - t^{\text{Phan}})}{n} \right]. \quad (2)$$

Statistical Analyses

Descriptive statistics were calculated by using statistical software (SPSS 11.5 for Windows 2002; SPSS, Chicago, Ill). Specifically, RMS errors and mean residual errors were averaged for the 3 days on which the CT exami-

nations were conducted. The resulting mean values, with corresponding standard deviation error bars, were plotted (SigmaPlot 8.0; Systat Software, San Jose, Calif) to determine the interscan variation in reconstruction error.

Results

Contrast-enhanced CT

There were notable differences in average RMS error and mean residual error due to alterations in contrast agent con-

centration (Fig 2). Simulated phantom cartilage thicker than 1.0 mm was reconstructed with less than 10% RMS error and mean residual error when the lowest contrast agent concentration (25%) was used and the direction of CT scanning was transverse to the phantom (Fig

Figure 2

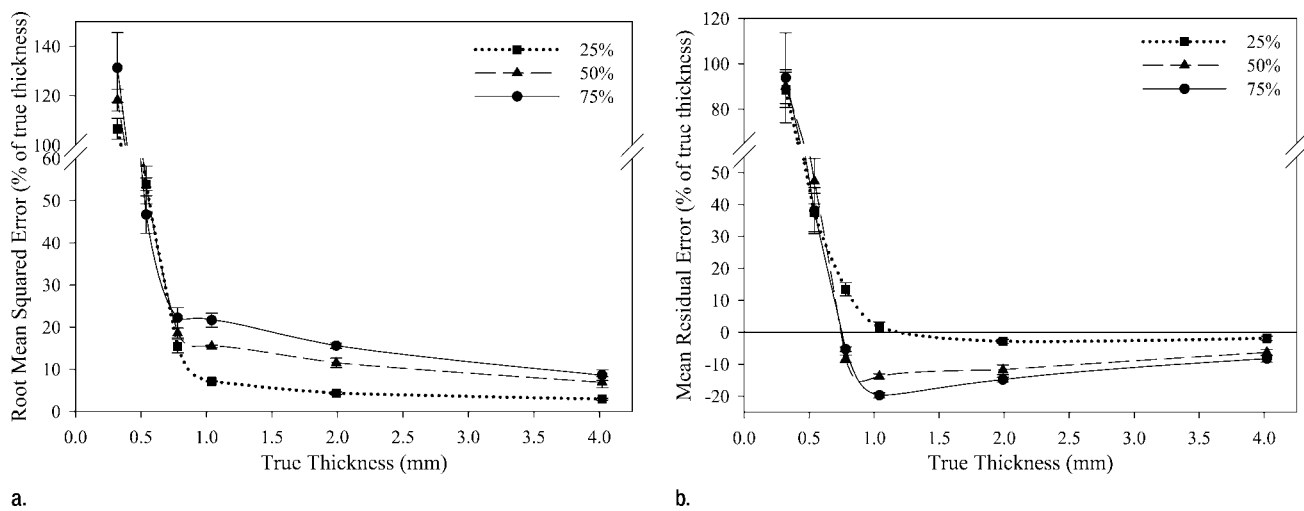


Figure 2: Graphs illustrate simulated cartilage (a) RMS and (b) mean residual reconstruction errors for transverse contrast-enhanced CT data sets, as a function of contrast agent concentration. (a) At cartilage thicknesses greater than 0.75 mm, RMS errors increased progressively as the contrast agent concentration increased. Direction of error was dependent on contrast agent concentration and simulated cartilage thickness.

Figure 3

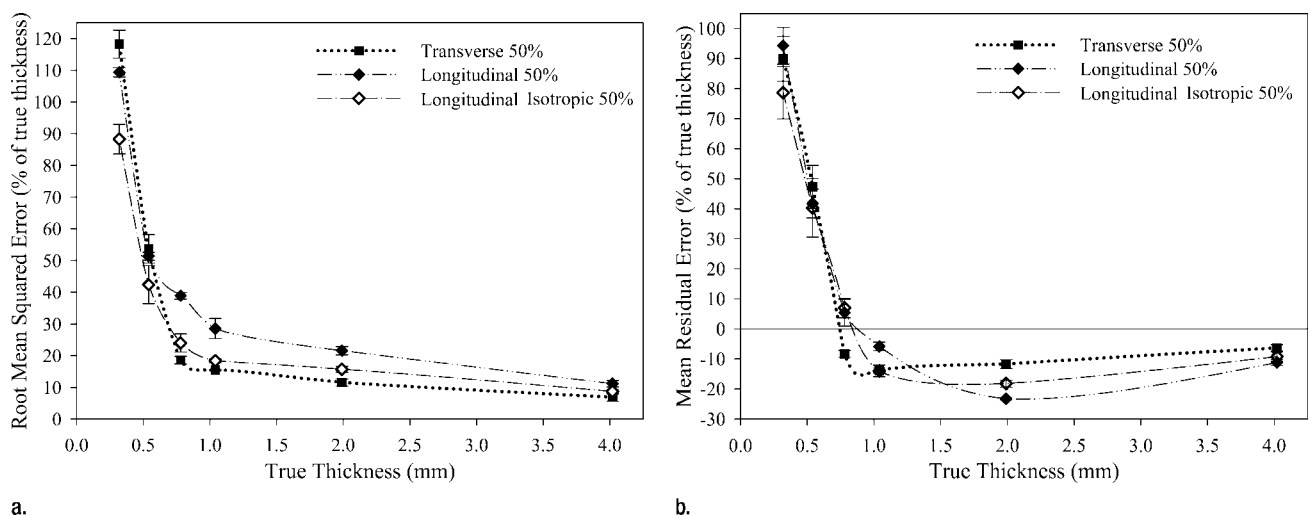


Figure 3: Graphs illustrate simulated cartilage (a) RMS and (b) mean residual reconstruction errors for transverse contrast-enhanced CT data sets obtained with 50% contrast agent concentration, as a function of scanning direction and spatial resolution. Errors were greatest for the anisotropic longitudinal data reconstructions. The isotropic longitudinal reconstructions yielded errors more consistent with transverse CT results.

2). At cartilage thicknesses greater than 0.75 mm, transverse CT-derived RMS reconstruction errors increased progressively as the contrast agent concentration was increased from 25% to 75% (Fig 2a). An increase in contrast agent concentration resulted in a greater tendency for simulated cartilage thicknesses of 1.0–4.0 mm to be underestimated (Fig 2b). However, a shift in error, from underestimation to overestimation, occurred as the cartilage thickness approached the spatial resolution of the image data (0.586×0.586 mm) (Fig 2b).

Substantial differences in average reconstruction errors were also noted when the scanning direction and spatial resolution were altered (Fig 3). For simulated cartilage thicker than 1.0 mm (Fig 3), anisotropic longitudinal reconstructions at the 50% contrast agent concentration yielded greater RMS and mean residual errors than did the corresponding transverse and near-isotropic longitudinal reconstructions at the 50% concentration. Finally, altering the tube current resulted in negligible differences over the range of simulated cartilage thicknesses analyzed (data not shown).

There were differences in RMS errors over the range of joint space widths assessed due to changes in contrast agent concentration and scanning direction (Fig 4) but no marked differences due to alterations in tube current (data not shown). Errors increased as the contrast agent concentration was in-

creased (Fig 4). For each transverse CT measurement, RMS errors increased slightly when the joint space width was decreased from 2.0 to 0.5 mm; at widths lower than 0.5 mm, however, errors increased substantially (Fig 4). The anisotropic longitudinal CT data set (1.0-mm thickness reconstruction) yielded greater RMS errors than did the corresponding transverse and near-isotropic longitudinal data sets (0.5-mm thickness reconstruction) over the full range of joint space widths analyzed (Fig 4). Mean residual error analysis revealed that simulated cartilage thickness was underestimated in all data sets and that these errors were the smallest with transverse 25%-concentration CT scanning (data not shown).

Examination of the standard deviation error bars in Figures 2–4 revealed high levels of reproducibility for measurements of 0.75–4.00-mm-thick simulated cartilage. In addition, the standard deviation error bars and adjacent results within this range did not overlap. For measurements of 0.25–0.50-mm-thick simulated cartilage, standard deviations were much larger and error bars and adjacent data points overlapped.

Nonenhanced CT

Reconstructions of nonenhanced transverse CT data at 200 mAs resulted in RMS errors of less than 10% for measurements of cartilage thicker than 1.0 mm (Fig 5a). RMS errors in the nonen-

hanced CT data were within 2% of those reported for transverse contrast-enhanced scanning of 0.75–4.00-mm-thick simulated cartilage at the 25% contrast agent concentration. RMS errors in measurements of simulated cartilage less than 1.0 mm thick increased substantially, but they leveled out at thicknesses of 0.50–0.25 mm (Fig 5a). The leveling point on the RMS plot aligned well with corresponding points of inflection on the mean residual error plot (Fig 5b). Therefore, the lack of increase in RMS error at a thickness of 0.25 mm was due to a shift from underestimation to overestimation of cartilage thickness. RMS errors in the longitudinal and near-isotropic longitudinal data sets were similar to errors in the transverse measurements of 2.0- and 4.0-mm-thick simulated cartilage; however, errors increased substantially at thicknesses of less than 2.0 mm (Fig 5a). Errors in longitudinal anisotropic CT measurements were substantially greater than errors in transverse and near-isotropic longitudinal CT measurements of simulated cartilage less than 2.0 mm thick (Fig 5a). Altering the tube current from 150 to 250 mAs did not have an appreciable effect on RMS or mean residual errors in the transverse plane (data not shown).

Like the standard deviation error bars for contrast-enhanced CT scanning, the standard deviation error bars for nonenhanced scanning were negligible for measurements of the thicker (0.75–4.00 mm) simulated cartilage, but they were larger when the thickness was decreased to below this range. In addition, standard deviation error bars did not overlap with adjacent data points within this thickness range, but they did at cartilage thicknesses of less than 0.75 mm.

Discussion

To our knowledge, our study is the first in which the detection limits of multidetector CT were quantified by using a phantom. Simulated cartilage thicker than 1.0 mm was reconstructed with less than 10% RMS and mean residual

Figure 4

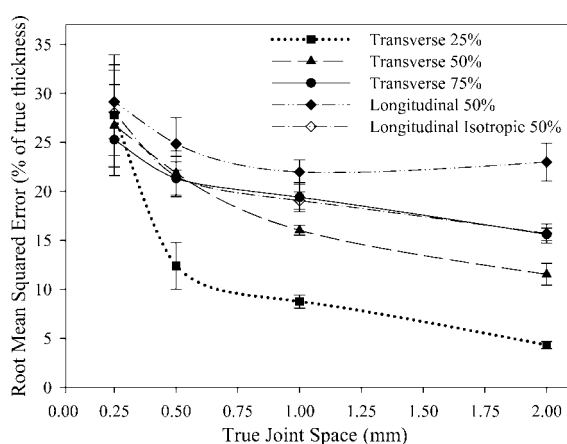


Figure 4: Graph illustrates simulated cartilage RMS errors as a function of joint space width, contrast agent concentration, scanning direction, and spatial resolution. Errors increased as contrast agent concentration increased. There were fewer reconstruction errors in the isotropic longitudinal data set than in the anisotropic data set in the same imaging plane.

Figure 5

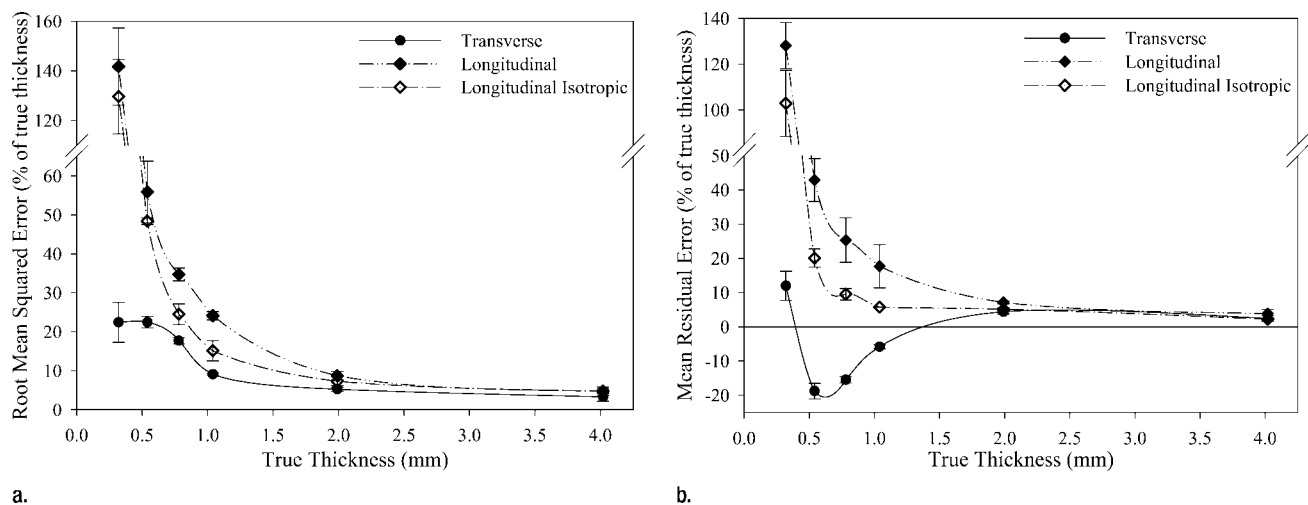


Figure 5: Graphs illustrate simulated cartilage (a) RMS and (b) mean residual reconstruction errors for the nonenhanced CT data sets obtained at 200 mAs, as a function of scanning direction and spatial resolution. There were consistently fewer RMS errors in the isotropic longitudinal data set than in the anisotropic data set for measurements of simulated cartilage less than 2.0 mm thick.

errors when either no contrast agent or a low concentration (25%) of contrast agent was used. Our study results also demonstrate that the CT reconstruction errors were dependent on contrast agent concentration, scanning direction, spatial resolution, and to a lesser extent joint spacing. Alterations in scanner tube current did not substantially affect simulated cartilage thickness reconstruction errors at the thickness ranges tested at both contrast-enhanced and nonenhanced CT.

Care was taken to control confounding factors in our study. The physical thickness of the phantom was measured to a tolerance of ± 0.07 mm; thus, variations in the true thickness of the phantom did not have a substantial influence on the perceived phantom thickness measured with CT. In addition, a separate examination was performed whenever a new alteration (eg, in scanning direction, tube voltage, or contrast agent concentration) was applied to isolate specific effects. The entire protocol was repeated on separate days, and only minor interscan variations in measurements of 0.75–4.00-mm-thick simulated cartilage were noted at both contrast-enhanced and nonenhanced scanning. Therefore, within this thickness range, any noted differences in re-

construction error were due to the alteration studied rather than to confounding factors such as CT scanner variability.

The results of the contrast-enhanced CT reconstructions show a direct relationship between contrast agent concentration and reconstruction error. An explanation for this is that as the contrast agent concentration was increased, larger pixel attenuation gradients were established at the boundary between cartilage and contrast agent. This phenomenon initiated more intense volumetric averaging at this boundary and resulted in a greater tendency for cartilage thickness to be underestimated. However, a shift in error, from underestimation to overestimation, occurred as the thickness approached the spatial resolution of the image data (0.586×0.586 mm). This shift occurred because the thickness could not decrease much below the width of a single pixel without extensive surface decimation and smoothing. Therefore, although CT has been shown to yield overestimations of the thickness of thin structures (25,26), our study results demonstrate that the direction of the error is dependent on the concentration of fluid in the joint and the spatial reso-

lution of the image data when CT arthrography is used.

El-Khoury et al (6) compared ankle cartilage measurements obtained with double-contrast multidetector CT arthrography and three-dimensional fat-suppressed spoiled gradient-recalled acquisition in the steady state MR imaging with physical measurements of 15 plugs excised from cadaveric ankles (1–2 mm thick); they found that CT was more accurate than MR imaging. Differences in segmentation method, joint geometry, and arthrography technique (use of double vs single contrast agent) between that study and our current investigation make exact comparisons impossible. Nevertheless, the best-fit line of physical plug measurements plotted against multidetector CT estimates in the El-Khoury et al study indicated that cartilage thickness was underestimated by approximately 5% with CT (6), which is consistent with the 25% concentration agent results over the same range of thicknesses in our study.

In terms of limitations, our study results must be interpreted with consideration of the inherent differences between measurements obtained from a phantom and those obtained in experimental studies with real cartilage specimens. It is well known that articular

cartilage exhibits depth- and location-dependent inhomogeneities in material structure (36–38), and these factors were not a part of our study design. In addition, although real tissue and the materials used for our phantom are similar (25–28), they have small differences in x-ray attenuation values. Finally, diarthrodial joints such as the shoulder and hip have spherical geometry, but the phantom chambers that we used were cylindrical. Nevertheless, our approach enabled us to eliminate potentially confounding factors such as geometry, tissue homogeneity, and measurement technique. In addition, three CT examinations were performed, and descriptive statistics were used to assess reproducibility; this statistical method is consistent with that in a previous phantom study of MR-measured section thickness (39).

For the chambers with simulated thicknesses of 0.25 and 0.50 mm, it was necessary to use a semiautomatic method to segment the simulated cartilage from the contrast-enhanced data sets. The reconstruction errors in the measurements of these chambers could have been influenced by user technique. However, the magnitude of the standard deviation error bars for thicknesses within this range was similar to that for thicknesses measured at nonenhanced CT, for which a purely automatic segmentation technique was used. Therefore, it appears that simulated cartilage reconstruction errors for thickness in this range would be high, regardless of the reconstruction technique used. Thus, caution should be exercised when making conclusions regarding thin cartilage (<0.75 mm in our phantom study).

The phantom was designed to simulate the interface between cartilage and cortical bone. There probably was some thinning of the polycarbonate at imaging due to volumetric averaging between the polycarbonate and the adjacent aluminum cylindrical sleeve. However, the thickness of the aluminum sleeve wall was kept constant for each phantom cylinder, and the thresholding protocol was not biased toward changes between phantom chambers or whole data sets. Therefore, any errors introduced were

consistent across all data sets, and, thus, simulated cortical bone was eliminated as a confounding factor.

From a basic science point of view, the following conclusion can be made: Since in our study errors were similar between the nonenhanced and contrast-enhanced (25% concentration) CT data sets, one can expect similar cartilage reconstruction errors when cadaveric tissues are CT scanned with or without contrast agent, assuming that a sufficient joint space is maintained and a low contrast agent concentration is used. However, given the additional technical challenges of keeping joint fluid within the capsule of a dissected joint, it seems more appropriate to scan the specimen without contrast agent.

In conclusion, the ability to reconstruct simulated cartilage by using a phantom and multidetector CT with and without arthrography is dependent on several factors, including contrast agent concentration, joint spacing, scanning direction, and spatial resolution. An improved understanding of the detection limits of multidetector CT cartilage reconstruction will assist in the diagnosis of joint abnormalities, interpretation of biomechanical models, and design of epidemiologic studies to investigate changes in cartilage thickness.

Practical applications: Our study results provide minimal boundaries for errors in multidetector CT measurements of cartilage thickness, as well as guidelines for practical use. It must be emphasized that the reported phantom reconstruction errors are probably best-case results since confounding factors were controlled. Higher contrast agent concentrations caused the simulated cartilage depicted on the CT images to appear thinner than the reference thickness; thus, use of a lower contrast agent concentration is likely to reduce the amount of volumetric averaging between actual cartilage and contrast agent. In addition, joint spacing should be maximized before CT scanning; this can be done by completely filling the joint capsule with diluted contrast solution and/or by applying traction to the joint. Failure to do this will result in increased errors when the width of the

joint space reaches a critical threshold (0.5 mm in our phantom study). Finally, CT image reconstructions should be chosen such that isotropic or near-isotropic spatial resolution is achieved. Multidetector CT, unlike previous CT modalities, offers the ability to do this without increasing the radiation dose to the patient (40).

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