Math 5760/6890: Introduction to Mathematical Finance

2-Security Markowitz Efficient Frontier

See Petters and Dong 2016, Section 3.2

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A quick recap

D09-S02(a)

For Markowitz 2-security portfolio optimization:

- Return rates $oldsymbol{R}$ for the two securities are random variables
- Assume first- and second-order statistics of these are available: $m\mu=\mathbb{E}m R$ and $\mathrm{Cov}(m R)$
- The portfolio is defined by the weights $oldsymbol{w}$
- The expected return rate of the portfolio is $\mu_P = \langle oldsymbol{\mu}, oldsymbol{w}
 angle$
- The squared risk of the portfolio is $\sigma_P^2 = \operatorname{Var} \langle {m R}, {m w} \rangle = {m w}^T \operatorname{Cov}({m R}) {m w}$

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D09-S02(b)

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We typically seek a risk-optimal portfolio for a given target mean μ_P :

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\min_{\boldsymbol{w}} \boldsymbol{w}^T \boldsymbol{A} \boldsymbol{w} \text{ subject to } \langle \boldsymbol{w}, \boldsymbol{1} \rangle = 1, \text{ and}\langle \boldsymbol{w}, \boldsymbol{\mu} \rangle = \mu_P.
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 $\underline{A} = Cov(\underline{R})$

- We can formulate an optimization that minimizes risk at a given expected return rate.
- There is typically only one feasible portfolio, hence it's optimal.
- The resulting optimized risk can be *much* lower than the individual security risks.
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Today: efficient portfolios and the efficient "frontier".

D09-S04(a)

Example

Consider the problem of constructing a (Markowitz) 2-security portfolio. The individual securities have expected return rates and covariance given by,

$$\mathbb{E}\boldsymbol{R}(T) = \begin{pmatrix} 2\\ 6 \end{pmatrix}, \qquad \qquad \operatorname{Cov}\boldsymbol{R}(T) = \begin{pmatrix} 2 & -1\\ -1 & 2 \end{pmatrix}$$

We've computed the risk-optimal portfolio as a function of μ_P :

$$\boldsymbol{w} = \begin{pmatrix} \frac{6-\mu_P}{\frac{\mu^2}{4}} \\ \frac{\mu^2-2}{4} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 3 \\ -1 \end{pmatrix} + \frac{\mu_P}{4} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

D09-S04(b)

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And we've used this to determine the optimal risk σ_P for a fixed μ_P :

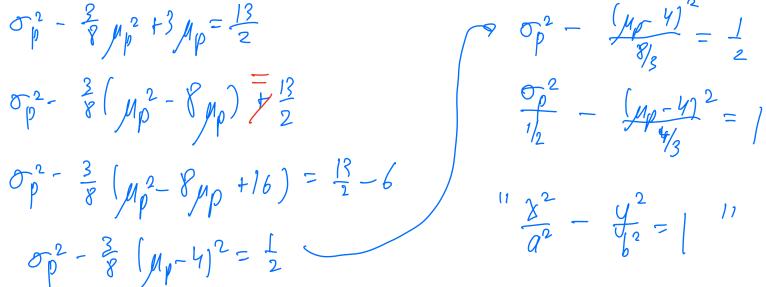
$$\sigma_P^2 = \frac{3}{8}\mu_P^2 - 3\mu_P + \frac{13}{2}$$

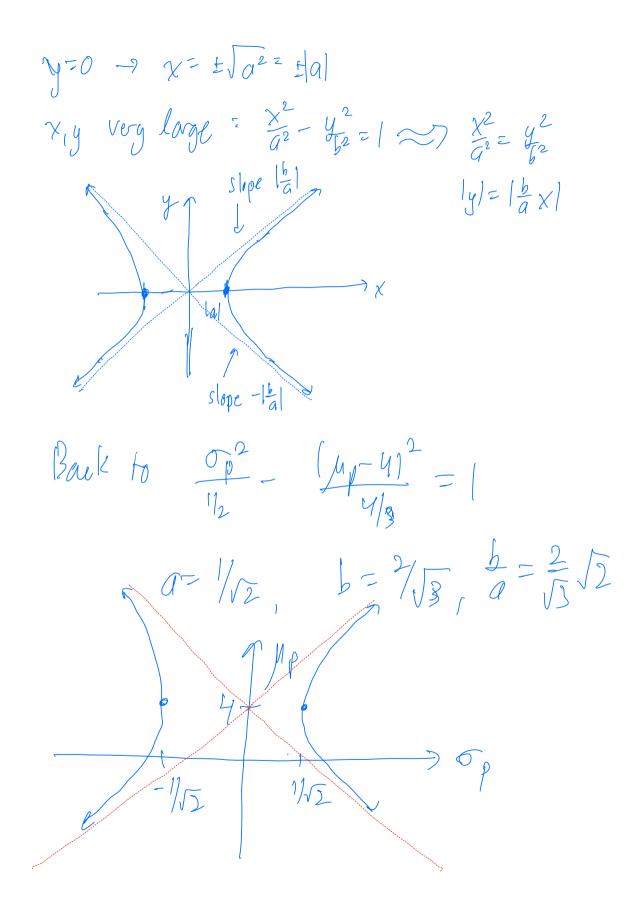
Optimal portfolios

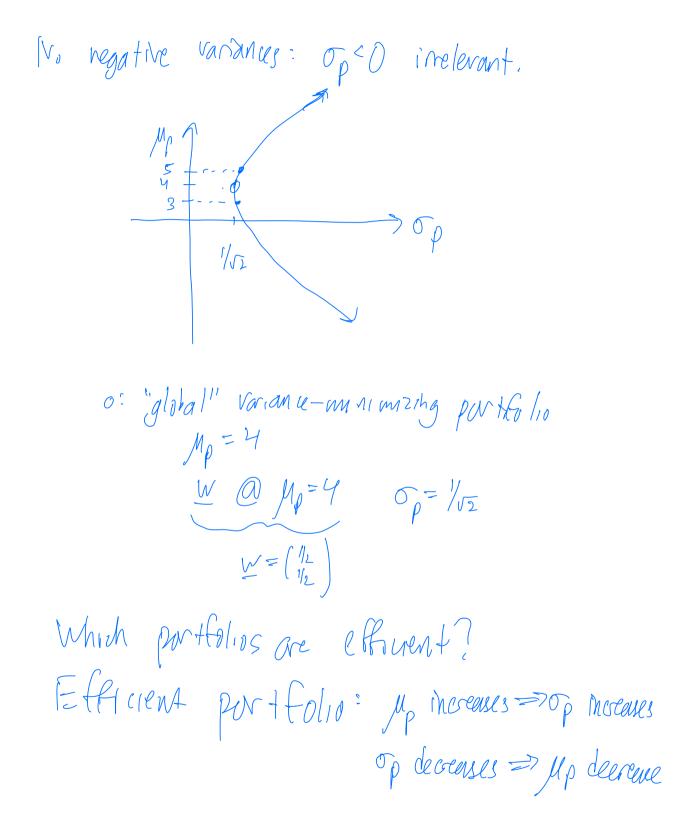
D09-S05(a)

$$\sigma_P^2 = \frac{3}{8}\mu_P^2 - 3\mu_P + \frac{13}{2}$$

This relationship can be used to identify the set of all possible risk-optimal portfolios as a graph of valid (σ_P, μ_P) pairs.







"In math": $\frac{d\sigma p}{d\mu p} > 0$ $\frac{dMp}{d\sigma p} > 0$ => Efficient purtfolios are the "upper half" of the hyperbola efficient portfolios "efficient frontier" rihefficient portfolios 1/B

The particular aspects we've explored in the previous example are generic:

- The set of risk-optimal portfolios is defined by the graph of a hyperbola in the (σ_P, μ_P) plane.
- The upper half of this graph are efficient portfolios the efficient frontier.

The particular aspects we've explored in the previous example are generic:

- The set of risk-optimal portfolios is defined by the graph of a hyperbola in the (σ_P, μ_P) plane.
- The upper half of this graph are efficient portfolios the *efficient frontier*.
- There is a *global* risk-optimal portfolio, which corresponds to a particular expected return rate.
- In the (general) 2-security model, any feasible portfolio is risk-optimal.¹

¹This is not true if $\mu_1 = \mu_2$.

The general 2-security case

The previous aspects hold in the general 2-security case, assuming $\mu_1 = \mu_2$ and a positive-definite covariance.

Example

Consider the general 2-security setup:

$$\boldsymbol{\mu} = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \qquad \qquad \boldsymbol{A} = \operatorname{Cov}(\boldsymbol{R}),$$

where A is positive-definite and $\mu_1 \neq \mu_2$. Show that risk-optimal portfolios are given by the locus of points (σ_P, μ_P) satisfying,

$$\frac{\sigma_P^2}{a^2} - \frac{(\mu_P - \mu_G)^2}{b^2} = 1.$$

where a, b, μ_G are explicit constants: μ_G is the expected return rate of the global risk-optimal portfolio.

weight votors are unique? $w_i t w_2 = 1$ $M_i w_1 + M_2 w_2 = M_p$

$$= \sum_{M_{2}=M_{1}} \left(\begin{array}{c} M_{2}-M_{1} \\ M_{1}-M_{1} \end{array} \right) = \underbrace{V_{0}}_{} + \underbrace{M_{1}}_{} \underbrace{M_{2}-M_{1}}_{} \\ \underbrace{V_{0}}_{} = \underbrace{-\frac{1}{M_{2}-M_{1}}}_{} \left(\begin{array}{c} M_{2} \\ -M_{1} \end{array} \right) \\ \underbrace{V_{1}}_{} = \underbrace{-\frac{1}{M_{2}-M_{1}}}_{} \left(\begin{array}{c} -1 \\ 1 \end{array} \right)$$

$$\sigma_{p}^{2} = \underbrace{\psi^{\dagger} \underbrace{A} \psi}_{=} \underbrace{(\underbrace{v}_{0} + \underbrace{v}_{1}, \mu_{p})^{\dagger} \underbrace{A} (\underbrace{v}_{0} + \underbrace{v}_{1}, \mu_{p})}_{= \mu_{p}^{2} (\underbrace{v}_{1}^{\dagger} \underbrace{A} \underbrace{v}_{1}) + 2\mu_{p} (\underbrace{v}_{1}^{\dagger} \underbrace{A} \underbrace{v}_{0}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v}_{0}}_{= \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v}_{1}}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v}_{0}}_{\underbrace{v_{1}^{\dagger} \underbrace{A} \underbrace{v}_{1}}, \underbrace{\mu_{p}^{2} + \underbrace{2\underbrace{v}_{1}^{\dagger} \underbrace{A} \underbrace{v}_{0}}_{\underbrace{v_{1}^{\dagger} \underbrace{A} \underbrace{v}_{1}}, \mu_{p}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v_{0}}_{\underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v}_{0}}_{\underbrace{v_{1}^{\dagger} \underbrace{A} \underbrace{v}_{1}}, \mu_{p}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v_{0}}_{\underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v}_{0}}_{\underbrace{v_{1}^{\dagger} \underbrace{A} \underbrace{v}_{1}}, \mu_{p}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v_{0}}_{\underbrace{v}_{0}}, \mu_{p}) + \underbrace{v_{0}^{\dagger} \underbrace{A} \underbrace{v_{0}}_{\underbrace{v}}, \mu_{p}) + \underbrace{v_{0}^{\dagger} \underbrace{v_{0}}_{\underbrace{v}}, \mu_{p}) + \underbrace{$$

$$\Rightarrow \frac{\nabla_{p}^{2}}{Q^{2}} - \frac{\left(M_{p} - M_{b}^{2}\right)^{2}}{b^{2}} = 1 , \qquad M_{b}^{2} = \frac{-V_{v}^{\dagger} A_{v_{b}}}{V_{v}^{\dagger} A_{v_{i}}}$$

$$a^{2} = V_{0}^{\dagger} A_{v_{0}} - \frac{\left(V_{v}^{\dagger} A_{v_{0}}\right)^{2}}{V_{v}^{\dagger} A_{v_{i}}} (>0)$$

$$b^{2} = \frac{a^{2}}{V_{v}^{\dagger} A_{v_{i}}}$$

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In practice, we may want to disallow short selling to avoid such situations.

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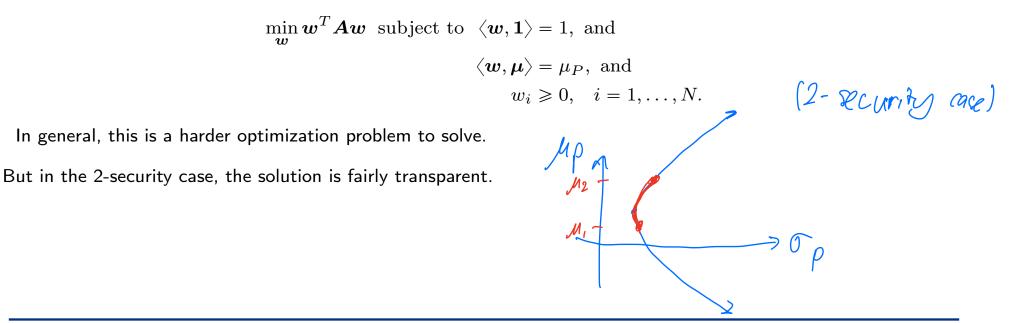
The corresponding optimization problem is an augmentation of what we've already seen:

 $\min_{\boldsymbol{w}} \boldsymbol{w}^T \boldsymbol{A} \boldsymbol{w} \text{ subject to } \langle \boldsymbol{w}, \boldsymbol{1} \rangle = 1, \text{ and}$ $\langle \boldsymbol{w}, \boldsymbol{\mu} \rangle = \mu_P, \text{ and}$ $w_i \ge 0, \quad i = 1, \dots, N.$

For general $\mathbb{E}\mathbf{R}$, $\operatorname{Cov}(\mathbf{R})$, μ_P , the risk-optimal portfolio could be highly leveraged (even if it's efficient).

In practice, we may want to disallow short selling to avoid such situations.

The corresponding optimization problem is an augmentation of what we've already seen:



In the 2-security case:

- Generally, no optimization is needed for 2-security portfolios: the weight constraints uniquely identify portfolios
- Many risk-optimal portfolios are not efficient
- The set of risk-optimal portfolios can be explicitly parameterized + plotted
- There is a global variance-minimizing portfolio investors might not want this portfolio.

Many of the lessons we've learned from 2-security portfolios will hold in the N-security case:

- Risk-optimal portfolios can be computed and plotted
- The efficient frontier is visually identifiable
- There is a globally risk-optimal portfolio

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- Risk-optimal portfolios can be computed and plotted
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There are some differences that make things more complicated:

- Optimization is generally required
- There are (many) feasible portfolios that are not risk-optimal
- Explicit pen+paper computations become harder

D09-S10(b)



Petters, Arlie O. and Xiaoying Dong (2016). An Introduction to Mathematical Finance with Applications: Understanding and Building Financial Intuition. Springer. ISBN: 978-1-4939-3783-7.