

Analysis of Numerical Methods I
MATH 6610 – Section 001 – Fall 2025

Homework 6
Conditioning and LU

Due Wednesday, October 1, 2025

Submission instructions:

Submit your assignment on gradescope.

Problem assignment:

1. (Least squares problems) Let $\mathbf{A} \in \mathbb{C}^{m \times n}$ and $\mathbf{b} \in \mathbb{C}^m$ be given. $\mathbf{A}^+$ denotes the Moore-Penrose pseudoinverse of $\mathbf{A}$.

- (a) Assume $\text{rank}(\mathbf{A}) = n$. Prove that $\mathbf{x} = \mathbf{A}^+\mathbf{b}$ solves the least squares problem,

$$\underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{Ax} - \mathbf{b}\|_2$$

- (b) Show that when $\text{rank}(\mathbf{A}) = n$, the least squares solution $\mathbf{x}$ equivalently is the unique solution to the *normal equations*, $\mathbf{A}^*\mathbf{Ax} = \mathbf{A}^*\mathbf{b}$.

- (c) For general $\mathbf{A}$, prove that $\mathbf{x} = \mathbf{A}^+\mathbf{b}$ solves the minimum-norm least squares problem,

$$\min \|\mathbf{x}\|_2 \text{ subject to } \|\mathbf{Ax} - \mathbf{b}\|_2 \text{ is minimized}$$

2. (ϵ -pseudospectrum) Let $\mathbf{A} \in \mathbb{C}^{n \times n}$. We let $\Lambda(\mathbf{A})$ denote the spectrum (set of eigenvalues) of $\mathbf{A}$. For some $\epsilon > 0$, the ϵ -pseudospectrum of $\mathbf{A}$ is the set of complex numbers $\Lambda_\epsilon(\mathbf{A}) \subset \mathbb{C}$ given by

$$\Lambda_\epsilon(\mathbf{A}) := \{z \in \mathbb{C} \mid z \in \Lambda(\mathbf{A} + \Delta\mathbf{A}) \text{ for some } \Delta\mathbf{A} \in \mathbb{C}^{n \times n} \text{ satisfying } \|\Delta\mathbf{A}\|_2 \leq \epsilon\}.$$

Another concept we'll need is the *resolvent*. The resolvent of $\mathbf{A}$ at $z \in \mathbb{C}$ is defined as the matrix $\text{Res}_{\mathbf{A}}(z) := (z\mathbf{I} - \mathbf{A})^{-1}$.

Given $\epsilon > 0$ and $\mathbf{A} \in \mathbb{C}^{n \times n}$, prove that the following three sets of numbers in the complex plane are identical:

- (a) $\Lambda_\epsilon(\mathbf{A})$
 - (b) The set of $z \in \mathbb{C}$ satisfying $\|(\mathbf{A} - z\mathbf{I})\mathbf{v}\|_2 \leq \epsilon$ for some unit vector $\mathbf{v}$.
 - (c) $\{z \in \mathbb{C} \mid \|\text{Res}_{\mathbf{A}}(z)\|_2 \geq 1/\epsilon\}$, with the convention that $\|\text{Res}_{\mathbf{A}}(z)\|_2 = \infty$ if $z \in \Lambda(\mathbf{A})$.
3. (Bauer-Fike eigenvalue perturbations) Suppose $\mathbf{A} \in \mathbb{C}^{n \times n}$ is diagonalizable with eigenvalue decomposition $\mathbf{A} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^{-1}$. Let $\Delta\mathbf{A}$ be any matrix satisfying $\|\Delta\mathbf{A}\|_2 \leq \epsilon$. Suppose $\tilde{\lambda}$ is an(y) eigenvalue of $\mathbf{A} + \Delta\mathbf{A}$. Show that there is some eigenvalue $\lambda \in \Lambda(\mathbf{A})$ such that

$$|\lambda - \tilde{\lambda}| \leq \epsilon \kappa(\mathbf{V}),$$

with $\kappa(\mathbf{V})$ the (2-norm) condition number of $\mathbf{V}$. The typical way to prove this is to exploit the equivalence of sets defining the ϵ -pseudospectrum. (E.g., rewrite the resolvent with the knowledge that $\mathbf{A}$ is diagonalizable.). If $\mathbf{A}$ is unitarily diagonalizable, what does the bound above simplify to?

4. (LU with partial pivoting) Let $\mathbf{A} \in \mathbb{C}^{n \times n}$ be invertible. Prove that the row-pivoted LU decomposition algorithm always successfully computes $\mathbf{PA} = \mathbf{LU}$.
5. (Schur complements) Consider the block matrix

$$\mathbf{M} = \begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{pmatrix},$$

where $\mathbf{A} \in \mathbb{C}^{m \times m}$, $\mathbf{D} \in \mathbb{C}^{n \times n}$, and $\mathbf{B}$ and $\mathbf{C}$ have appropriate (generally rectangular) size. Throughout this problem, assume that both $\mathbf{A}$ and $\mathbf{D}$ are invertible. This problem concerns, among other things, computing the solution vectors to a linear system involving $\mathbf{M}$. The *Schur complement* of the block $\mathbf{A}$ of the matrix $\mathbf{M}$ is defined as

$$\mathbf{M}/\mathbf{A} := \mathbf{D} - \mathbf{CA}^{-1}\mathbf{B} \in \mathbb{C}^{n \times n},$$

Similarly, $\mathbf{M}/\mathbf{D} := \mathbf{A} - \mathbf{BD}^{-1}\mathbf{C}$ is the Schur complement of $\mathbf{D}$ of the matrix $\mathbf{M}$. For this problem, you will be performing block matrix operations; in particular, block matrix multiplication works like matrix multiplication with scalars. Perform the following exercises:

- (a) If $\mathbf{N}$ is a 2×2 matrix, then its LU decomposition can be determined by asserting the form,

$$\mathbf{N} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \mathbf{LU} = \begin{pmatrix} 1 & 0 \\ w & 1 \end{pmatrix} \begin{pmatrix} x & y \\ 0 & z \end{pmatrix},$$

and by performing matrix multiplication and solving for w, x, y, z , in terms of the entries of $\mathbf{N}$. Use this same idea to compute a block LU decomposition for $\mathbf{M}$ in terms of its blocks $\mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D}$.

- (b) Show that $\det \mathbf{M} = (\det \mathbf{A})(\det(\mathbf{M}/\mathbf{A}))$, and hence that $\mathbf{M}$ is invertible iff both $\mathbf{A}$ and $\mathbf{M}/\mathbf{A}$ are invertible. (NB: the familiar formula for the determinant of a 2×2 matrix isn't true for block matrices...but you could compute a block LDU decomposition.)
- (c) Assume $\mathbf{M}$ is Hermitian. Show that $\mathbf{M}$ is positive definite iff both $\mathbf{A}$ and $\mathbf{M}/\mathbf{A}$ are positive definite.
- (d) For generally non-Hermitian $\mathbf{M}$, given vectors $\mathbf{f} \in \mathbb{C}^m$ and $\mathbf{g} \in \mathbb{C}^n$, consider the following linear system:

$$\mathbf{M} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \mathbf{f} \\ \mathbf{g} \end{pmatrix}, \quad \mathbf{x} \in \mathbb{C}^m, \mathbf{y} \in \mathbb{C}^n.$$

Using the block LU decomposition of $\mathbf{M}$, give a formula for $\mathbf{x}$ and $\mathbf{y}$ that utilizes inverses of only $\mathbf{A}$ and $\mathbf{M}/\mathbf{A}$.